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## GENERAL SOLUTION OF A FUNCTIONAL EQUATION*

Dragomir Z̈. Djoković
We consider the functions defined on an arbitrary set $S$, which take their values in a certain abelian group $M$. The independent variables will be denoted by $x_{i}, i=1, \ldots, n$.

Let $C_{k}^{n}$ be the set of all strictly increasing mappings of the set $\{1,2, \ldots, k\}$ into $\{1,2, \ldots, n\}$. We shall solve the functional equation

$$
\begin{equation*}
\sum_{c \in C_{k}^{n}} f_{c}\left(x_{e(1)}, \ldots, x_{\varepsilon(k)}\right)=0 \quad(n>k>0) \tag{1}
\end{equation*}
$$

where all functions $f_{c}$ are unknown.
Theorem. The general solution of the functional equation (1) is given by

$$
\begin{equation*}
f_{c}\left(x_{c(1)}, \ldots, x_{c(k)}\right)=\sum_{s \in c_{k-1}^{k}} F_{c}^{s}\left(x_{c s(1)}, \ldots, x_{c s(k-1)}\right) \quad\left(c \in C_{k}^{n}\right) \tag{2}
\end{equation*}
$$

where $\operatorname{cs}(i)=c(s(i))$. The functions $F_{c}^{s}$ are arbitrary but subjected to the following conditions

$$
\begin{equation*}
\sum_{c s=t} F_{c}^{s}\left(x_{t(1)}, \ldots, x_{t(k-1)}\right)=0 \quad\left(t \in C_{k-1}^{n}\right) \tag{3}
\end{equation*}
$$

where the sum is extended over all $c$ and $s$ such that $c s=t$.
Proof. Let $f_{c}$ be defined by (2) and (3). Then we obtain

$$
\begin{aligned}
\sum_{c \in C_{k}^{n}} f_{c} & \left(x_{c(1)}, \ldots, x_{c(k-1)}\right) \\
& =\sum_{c \in C_{k}^{n}} \sum_{s \in c_{k-1}^{k}} F_{c}^{s}\left(x_{c s(1)}, \ldots, x_{c s(k-1)}\right) \\
& =\sum_{t \in C_{k-1}^{n}} \sum_{c s=t} F_{c}^{s}\left(x_{t(1)}, \ldots, x_{t(k-1)}\right) \\
& =0 .
\end{aligned}
$$

Hence, such functions satisfy the functional equation (1).

[^0]Conversely, if $f_{c}\left(c \in C_{k}^{n}\right)$ is any solution of (1) we have to prove that the functions $f_{c}$ admit the representation (2) with the conditions (3). Let us put in (1) $x_{i}=$ const if $i \neq c(j) \quad(j=1, \ldots, k)$ where $c$ is fixed. Then (1) gives

$$
\begin{equation*}
f_{c}\left(x_{c(1)}, \ldots, x_{c(k)}\right)=\sum_{s \in c_{k-1}^{k}} G_{c}^{s}\left(x_{c s(1)}, \ldots, x_{c s(k-1)}\right) . \tag{4}
\end{equation*}
$$

For any $t \in C_{k-1}^{n}$ let

$$
\begin{equation*}
H_{t}\left(x_{t(1)}, \ldots, x_{t(k-1)}\right)=\sum_{c s=t} G_{c}^{s}\left(x_{t(1)}, \ldots, x_{t(k-1)}\right) \tag{5}
\end{equation*}
$$

The equation (1) can be written in the form

$$
\begin{equation*}
\sum_{t \in c_{k-1}^{n}} H_{t}\left(x_{t(1)}, \ldots, x_{t(k-1)}\right)=0 \tag{6}
\end{equation*}
$$

Let $T^{\prime}$ be the set of all $t \in C_{k-1}^{n}$ such that $H_{t} \not \equiv 0$ and $T^{\prime \prime}=C_{k-1}^{n} \backslash T^{\prime}$. The equation (6) reduces to

$$
\begin{equation*}
\sum_{t \in T^{\prime}} H_{t}\left(x_{t(1)}, \ldots, x_{t(k-1)}\right)=0 . \tag{7}
\end{equation*}
$$

We can suppose that the number $r$ of elements of the set $T^{\prime}$ is taken to be minimal over all representations (4) of the functions $f_{c}$. If $r=0$ we can put $G_{c}^{s}=F_{c}^{s}$. The case $r=1$ is impossible since (7) holds. Therefore we can suppose that $r>1$. Let $t$ be some fixed element of $T^{\prime}$. Putting in (7) $x_{i}=$ const if $i \neq t(j) \quad(j=1, \ldots, k-1)$, we get

$$
\begin{equation*}
H_{t}\left(x_{t(1)}, \ldots, x_{t(k-1)}\right)=-\sum J_{c}^{s}\left(x_{t\left(i_{1}\right)}, \ldots, x_{t\left(i_{m}\right)}\right) \tag{8}
\end{equation*}
$$

where $J_{c}^{s}\left(x_{t\left(i_{1}\right)}, \ldots, x_{t\left(i_{m}\right)}\right)(m \leqslant k-2)$ is obtained from $G_{c}^{s}\left(x_{c s(1)}, \ldots, x_{c s(k-1)}\right)$ bi putting $x_{i}=$ const for all $i$ but $t(1), \ldots, t(k-1)$. The sum on the righthand side of (8) is extended over certain (not all) pairs of indices $c$ and $s$.

Consider a certain summand $J_{c_{0}}^{s_{0}}$ on the right-hand side of (8). Let $u_{0} \in C_{k}^{n}$ and $v_{0} \in C_{k-1}^{k}$ be such that $u_{0} v_{0}=t$. We can form a sequence of ordered pairs

$$
\left(u_{0}, v_{0}\right),\left(u_{0}, w_{0}\right),\left(u_{1}, v_{1}\right),\left(u_{1}, w_{1}\right), \ldots,\left(u_{p}, w_{p}\right)
$$

which satisfy the following conditions

$$
\begin{aligned}
& 1^{\circ} u_{i} \in C_{k}^{n}, v_{i} \in C_{k-1}^{k}, w_{i} \in C_{k-1}^{k} \\
& 2^{\circ}\left(u_{p}, w_{p}\right)=\left(c_{0}, s_{0}\right) \\
& 3^{\circ} u_{i-1} w_{i-1}=u_{i} v_{i} \quad(i=1, \ldots, p)
\end{aligned}
$$

$4^{\circ}$ the sequence $u_{i} w_{i}(1), \ldots, u_{i} w_{i}(k-1) \quad(i=0,1, \ldots, p)$ contains the sequence $t\left(i_{1}\right), \ldots, t\left(i_{m}\right)$ as a subsequence.

Let us put

$$
\begin{equation*}
\bar{G}_{u_{i}}^{v_{i}}=G_{u_{i}}^{v_{i}}+J_{c_{0}}^{s_{0}}, \quad \bar{G}_{u_{i}}^{w_{i}}=G_{u_{i}}^{w_{i}}-J_{c_{0}}^{s_{0}} \quad(i=0,1, \ldots, p) . \tag{9}
\end{equation*}
$$

We remark that (4) remains valid if we substitute $\bar{G}_{u_{i}}^{v_{i}}$ and $\bar{G}_{u_{i}}^{w_{i}}$ instead of $G_{u_{i}}^{v_{i}}$ and $G_{u_{i}}^{w_{i}}$, respectively. Also, if $w \in T^{\prime \prime}$ i. e. $H_{w} \equiv 0$ then also $\bar{H}_{w} \equiv 0$. Further, we have $\bar{H}_{t}=H_{t}+J_{c_{0}}^{s_{0}}$.

If the same procedure is applied to all summands of the right-hand member of (8), we conclude that the new function $H_{t}$ is identically zero. This contradicts the minimum property of $r$. Hence, $r=0$ which proves the theorem.

Example. If $n=4$ and $k=3$ the equation (1) is

$$
f\left(x_{1}, x_{2}, x_{3}\right)+g\left(x_{1}, x_{2}, x_{4}\right)+h\left(x_{1}, x_{3}, x_{4}\right)+i\left(x_{2}, x_{3}, x_{4}\right)=0 .
$$

Its general solution is given by

$$
\begin{gathered}
f\left(x_{1}, x_{2}, x_{3}\right)=f_{1}\left(x_{1}, x_{2}\right)+f_{2}\left(x_{1}, x_{3}\right)+f_{3}\left(x_{2}, x_{3}\right), \\
g\left(x_{1}, x_{2}, x_{4}\right)=g_{1}\left(x_{1}, x_{2}\right)+g_{2}\left(x_{1}, x_{4}\right)+g_{3}\left(x_{2}, x_{4}\right), \\
h\left(x_{1}, x_{3}, x_{4}\right)=h_{1}\left(x_{1}, x_{3}\right)+h_{2}\left(x_{1}, x_{4}\right)+h_{3}\left(x_{3}, x_{4}\right), \\
i\left(x_{2}, x_{3}, x_{4}\right)=i_{1}\left(x_{2}, x_{3}\right)+i_{2}\left(x_{2}, x_{4}\right)+i_{3}\left(x_{3}, x_{4}\right), \\
f_{1}\left(x_{1}, x_{2}\right)+g_{1}\left(x_{1}, x_{2}\right)=0, \\
f_{3}\left(x_{1}, x_{3}\right)+h_{1}\left(x_{1}, x_{3}\right)=0, \\
g_{3}\left(x_{2}, x_{4}\right)+i_{2}\left(x_{2}, x_{3}\right)=0, \\
\left.x_{2}, x_{4}\right)=0, \\
g_{2}\left(x_{1}, x_{4}\right)+h_{2}\left(h_{1}, x_{4}\right)=0, \\
\left.x_{4}, x_{4}\right)+i_{3}\left(x_{3}, x_{4}\right)=0 .
\end{gathered}
$$

Hence, we can take $f_{1}, f_{2}, f_{3}, g_{2}, g_{3}, h_{3}$ to be arbitrary and $g_{1}=-f_{1}, h_{1}=-f_{2}, i_{1}=-f_{3}$, $h_{2}=-g_{2}, i_{2}=-g_{3}, i_{3}=-h_{3}$.

Remark. This problem was raised recently by P. M. Vasić in the Institute of Mathematics of Belgrade. He has solved it for some special values of $k$. His solution is not given in the symmetric form.


[^0]:    * Presented December 20, 1964 by D. S. Mitrinović.

