

709. SOME QUADRATURE FORMULAS FOR ANALYTIC FUNCTIONS*

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In [1] the following formula for the numerical quadrature of analytic functions was derived:

$$(1) \quad \int_{-1}^1 f(z) dz = Af(0) + B(f(k) + f(-k)) + C(f(ik) + f(-ik)) + R,$$

where

$$A = 2 \left(1 - \frac{1}{5k^4} \right), \quad B = \frac{1}{6k^2} + \frac{1}{10k^4}, \quad C = -\frac{1}{6k^2} + \frac{1}{10k^4} \quad (k > 0)$$

and where the error-term was given by the expansion

$$R = \left(-\frac{2}{3 \cdot 6!} k^4 + \frac{2}{7!} \right) f^{(6)}(0) + \left(\frac{2}{9!} - \frac{2}{5 \cdot 8!} k^4 \right) f^{(8)}(0) + \dots$$

For $k=1$ BIRKHOFF-YOUNG's (BY) formula was obtained [2]; for $k = \sqrt{0.6}$ the GAUSS-LEGENDRE (GL) formula in three points was obtained since $C=0$ for that case; for $k = \sqrt[3]{3/7}$ the maximum accuracy formula, referred to as MF in [1] (modified BIRKHOFF-YOUNG's formula), was derived.

Formula (1) was derived under the assumption of equal absolute values of arguments of function f , i.e. that the corresponding points fall onto the center and vertices of a square in the complex plane. Notice that (1) can be derived using the method of undetermined coefficients, i.e. under the condition that $R=0$ for as high degree polynomials as possible. A more general problem can be formulated as follows:

Determine parameters A, B, C, x_1, x_2 in the formula

$$(2) \quad \int_{-1}^1 f(z) dz = Af(0) + B(f(x_1) + f(-x_1)) + C(f(ix_2) + f(-ix_2)) + R,$$

where the error-term R is to be annuled for polynomials of the maximum possible degree.

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For power functions of odd degree: z, z^3, z^5, \dots the error-term R is annuled. If we substitute functions $1, z^2, z^4, z^6$ and z^8 for f in (2), we obtain the following system:

$$(3) \quad \begin{aligned} \frac{A}{2} + B + C &= 1, & B x_1^2 - C x_2^2 &= \frac{1}{3}, & B x_1^4 + C x_2^4 &= \frac{1}{5}, \\ B x_1^6 - C x_2^6 &= \frac{1}{7}, & B x_1^8 + C x_2^8 &= \frac{1}{9}. \end{aligned}$$

REMARK 1. Coefficients of the *MF* formula are solutions of the first four equations of this system, where $x_1 = x_2$.

System (3) has no real solutions. One of its solutions corresponds to the *GL* formula in five points, when A, B, C, x_1 are real and x_2 purely imaginary, i.e. when the points are chosen on the real axis.

Solving the first four equations as a system, where it is the most suitable to choose x_2 as a parameter, we get:

$$\begin{aligned} x_1 &= \left(\frac{\frac{1}{5} x_2^2 + \frac{1}{7}}{\frac{1}{3} x_2^2 + \frac{1}{5}} \right)^{1/2}, & B &= \frac{\frac{1}{3} x_2^2 + \frac{1}{5}}{x_1^2 (x_1^2 + x_2^2)}, \\ C &= \frac{B x_1^2 - \frac{1}{3}}{x_2^2}, & A &= 2(1 - B - C). \end{aligned}$$

The error-term can be given in the form of TAYLOR series at $z = 0$, where the lead term R_1 is given by

$$(4) \quad R_1 = \frac{2}{8!} \left(\frac{1}{9} - B x_1^8 - C x_2^8 \right) f^{(7)}(0).$$

Parameter x_2 can be determined so that the coefficient multiplying $f^{(7)}(0)$ is minimized. This coefficient is a monotonically increasing function of x_2 . When x_2 tends to $+\infty$, then $C \rightarrow 0$, $x_1 \rightarrow \sqrt{0,6}$, $B \rightarrow \frac{5}{9}$, $A \rightarrow \frac{8}{9}$ and the *GL* formula in three points is obtained.

It is convenient to take $x_2 = 0.1$. Then using (3) we get

$$\begin{aligned} A &= 11.58360\ 728, & B &= 0.39508\ 64972, \\ C &= -5.18689\ 0135, & x_1 &= 0.84404\ 51279, \\ R_1 &= 4.6338 \cdot 10^{-7} \cdot f^{(7)}(0). \end{aligned}$$

This error-term is about 2.8 times smaller than the corresponding term in *MF*. For $x_2 < 0.1$ the absolute values of coefficients A and C increase. Therefore the obtained formulas are not suitable due to a possible increasing of roundoff errors.

By an analogous procedure we can develop the more general formula which includes *BY* and *MF*, as follows:

$$(5) \quad \int_{-1}^1 f(z) dz = Af(0) + B(f(x_1) + f(-x_1)) + C(f(ix_1) + f(-ix_1)) \\ + D(f(x_2) + f(-x_2)) + R.$$

By setting in (5) $f(z) = 1, z, z^2, \dots, z^8$, we obtain the system:

$$\begin{aligned} \frac{A}{2} + B + C + D &= 1, & Bx_1^2 - Cx_1^2 + Dx_2^2 &= \frac{1}{3}, \\ Bx_1^4 + Cx_1^4 + Dx_2^4 &= \frac{1}{5}, & Bx_1^6 - Cx_1^6 + Dx_2^6 &= \frac{1}{7}, \\ Bx_1^8 + Cx_1^8 + Dx_2^8 &= \frac{1}{9}. \end{aligned}$$

For example, if $x_1 = 1$, we get

$$\begin{aligned} x_2 &= 6.83130\,0511 \cdot 10^{-1}, & A &= 7.83673\,4695 \cdot 10^{-1}, \\ B &= 8.80952\,3810 \cdot 10^{-2}, & C &= -1.73160\,1731 \cdot 10^{-2}, \\ D &= 5.21799\,6289 \cdot 10^{-1}. \end{aligned}$$

For these coefficients using (5) we obtain in a simple case $I = \int_{-1}^1 e^x dx \approx 2.35040\,2393$, with the error about $5.77 \cdot 10^{-9}$.

REMARK 2. It is of interest to generalize formulas (2) and (5), by increasing the number of points.

REFERENCES

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NEKE KVADRATURNE FORMULE ZA ANALITIČKE FUNKCIJE

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U radu su izvedene dve kvadraturne formule za integraciju analitičkih funkcija. U ovim formulama se pojavljuju argumenti koji ne pripadaju segmentu integracije na realnoj osi, već su čisto imaginarni. Dobijene formule predstavljaju uopštenja do sada poznatih formula. U radu je sugerirana dalja generalizacija.